

# Computer Networks I

## Physical Layer

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## Overview

- 1 Basics
  - 1.1 Characteristics
  - 1.2 Bit Rate and Baud Rate
  - 1.3 Operating Modes
- 2 Analog and Digital Information Encoding and Transmission
- 3 Multiplexing Techniques

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Physical Layer

## Scope

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Physical Layer

Complementary Courses: Multimedia Systems, Distributed Systems, Mobile Communications, Security, Web, Mobile+UbiComp, QoS											
	Applications		P2P	Email	Files	Telnet	Web	IP-Tel: Signal. H.323 SIP	Media Data Flow	Security	
L5	Application Layer (Anwendung)	Transitions & Addressing	Internet: TCP, UDP				Mobile IP	Mobile Communications	MM COM - QoS specific		RT(C)P
L4	Transport Layer (Transport)		Internet: IP								Transport
L3	Network Layer (Vermittlung)		LAN, MAN High-Speed LAN, WAN				Network				
L2	Data Link Layer (Sicherung)										
L1	Physical Layer (Bitübertragung)		Other Lectures of "ET/IT" & Computer Science								
Introduction											

## 1 Basics

- Characteristics
- Bit Rate and Baud Rate
- Operating Modes

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Physical Layer

# 1.1 Characteristics

ISO DEFINITION: the physical layer provides the

- mechanical,
- electrical,
- functional and
- procedural

## FEATURES

to initiate, maintain and terminate physical CONNECTIONS BETWEEN

- Data Terminal Equipment (DTE) and
- Data Circuit Terminating Equipment (DCE, "postal socket")
- and/or data switching centers.

Using physical connections, the physical layer ensures the transfer of a TRANSPARENT BITSTREAM between DATA LINK LAYER-ENTITIES.

A PHYSICAL CONNECTION may permit either

- the duplex or
- the semi-duplex

transfer of a bitstream

## Characteristics

**MECHANICAL:** size of plugs, allocation of pins, etc.

- e. g. ISO 4903:
- data transfer - 15 pin DTE/DCE connection and pin allocation

**ELECTRICAL:** voltage levels on wires, etc.

- e. g. CCITT X.27/V.11:
- electrical features for the symmetrical transfer within the area of data communication

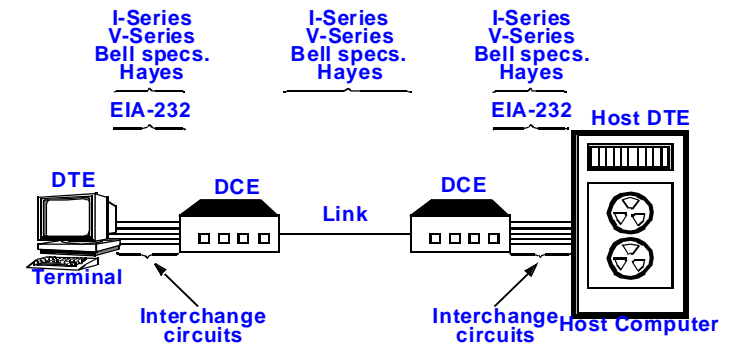
**FUNCTIONAL:** definition of switching functions; pin allocation (data, control, timing, ground)

- e. g. CCITT X.24:
- list of the switching functions between DTE und DCE in public data networks

**PROCEDURAL:** rules for using switching functions

- e. g. CCITT X.21:
- protocol between DTE and DCE for synchronized data transfer in public data networks

# Physical Layer



**DTE (Data Terminal Equipment = end-system)**

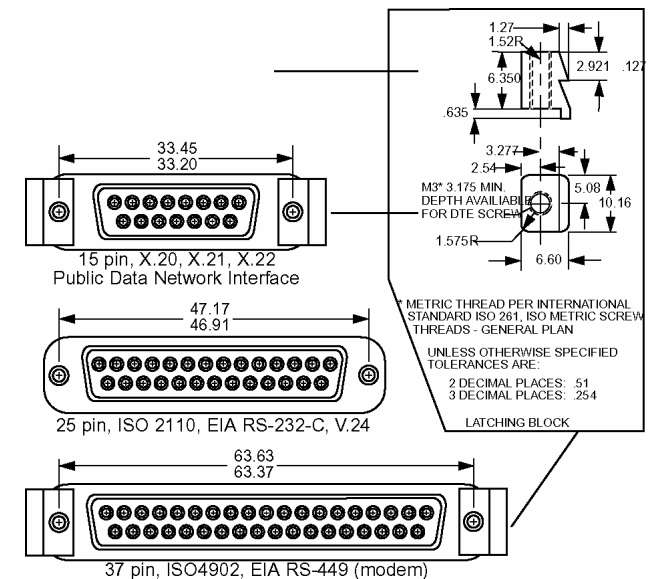
**DCE (Data Circuit-Terminating Equipment)**

- modem, multiplexer, Digital Service Unit

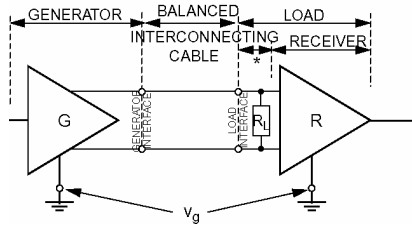
**Physical layer deals with interfaces between**

- DTE and DCE and
- DCE and DCE

## Mechanical

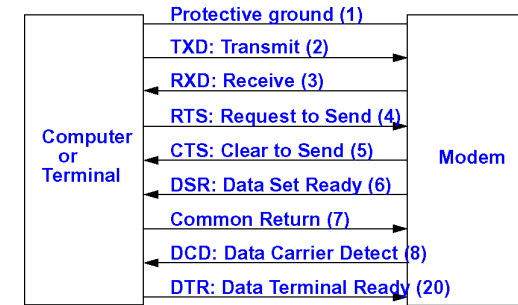


CCITT V.11 / X.27 (EIA RS -422-A)



e. g. ..."

- designed for IC Technology
- balanced generator
- differential receiver
- two conductors per circuit
- signal rate up to 10 Mbps
- distance: 1000m (at appr. 100 Kbps) to 10m (at 10Mbps)
- considerably reduced crosstalk
- interoperable with V.10 / X.26 ..."



Example RS-232-C, functional specification describes

- connection between pins
  - e.g. "zero modem" computer-computer-connection (Transmit(2) - Receive(3))
- meaning of the signals on the lines
  - DTR=1, when the computer is active, DSR=1, modem is active, ...
  - Action/reaction pairs specify the permitted sequence per event
  - e. g. when the computer sends an RTS, the modem responds with a CTS when it is ready to receive data

## 1.2 Bit Rate and Baud Rate

### BAUD RATE:

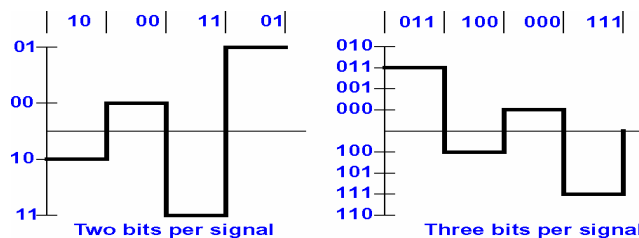
measure of number of symbols (characters) transmitted per unit of time

- signal speed, number of signal changes per second
  - changes in amplitude, frequency, phase
- each symbol normally consist of a number of bits
  - so the baud rate will only be the same as the bit rate when there is one bit per symbol.

**BIT RATE:** Number of Bits transferred per Second (bps)

- bit rate may be higher than baud rate ("signal speed")
  - because one signal value may transfer several bits

Example:



## Basics

**Bandwidth of a channel:**  $B = f_{max} - f_{min}$   
 $f_{max}$ ,  $f_{min}$  : maximum resp. minimum frequency

**Examples:**

- phone: min. 3000 Hz
- Coax: approx. 300 MHz
- fiber: approx.  $10^8$  MHz (visable light)

**Nyquist theorem (noise free channel)**

- max. bitrate =  $2 H \cdot \log_2 V$  bps
  - $H$ ... signal bandwidth (low pass filter)
  - $V$ ... discrete levels

**Example:**

- 3000 Hz channel, binary signal ( $V=2$ ):
  - max. bitrate = 6000 bps

## Basics

### Shannon theorem (noisy channel)

$$\text{max bitrate} = H \cdot \log_2 (1 + S/N)$$

- $H$ ... signal bandwidth (low pass filter)
- $S/N$  . . . Signal to Noise ratio
- $10 \log_{10} S/N$  *decibels*

### Example:

- 3000 Hz channel,
- $S/N = 1\ 000$  (30 dB)
  - max. bitrate = 30 000 bps

independent of number of levels !

This is an upper bound!

- real systems rarely achieve it

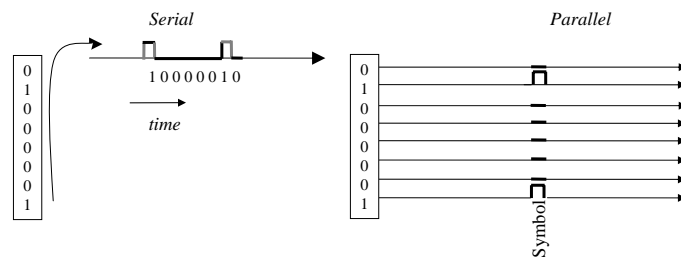
## 1.3 Operating Modes

Transfer directions (temporal parallelism)

- simplex communication:
  - data is always transferred into one direction only
- (half-duplex) semi-duplex communication
  - data is transferred into both directions
  - but never simultaneously
- full-duplex communication
  - data may flow simultaneously in both directions

## Serial and parallel transmission

- parallel:
  - signals are transmitted simultaneously over several channels
- serial:
  - signals are transmitted sequentially over one channel



## Operating Modes: Synchronous Transmission

### Definition

- the point in time at which the bit exchange occurs is pre-defined by a regular clock pulse (requires synchronization)
- whereby the clock pulse lasts as long as the transmission of a series of multiple characters takes

### Implementation

- receiving clock pulse
  - on a separate line (e. g. X.21) or
  - gained from the signal
- bit synchronous or frame synchronous (frames in fact on data link level)
  - special characters

e. g.  
SOH Start of Header  
STX Start of Text  
ETX End of Text

## Operating Modes: Asynchronous Transmission

### Definition

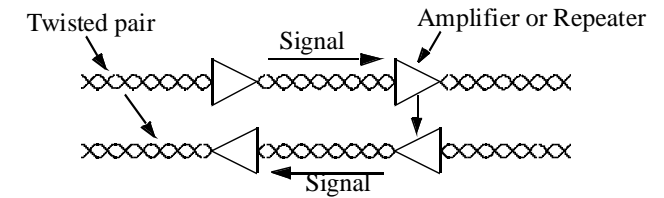
- clock pulse fixed for the duration of a signal
- termination marked by
  - Stop signal (bit) or
  - number of bits per signal

### Implementation

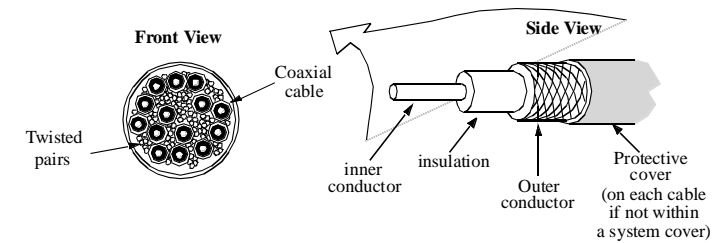
- simple:
  - sender and receiver generate the clock pulse independently from each other
- frame size usually approx. 9 bit (of this approx. 70% reference data)
  - example:
    - 7 Bit ASCII reference data
    - 1 Parity Bit (odd, even, or unused)
    - 1 Start-Bit
    - 1 Stop-Bit
- example: RS-232-C
  - UART (universal asynchronous receiver and transmitter) IC module
  - often between
    - computer and printer or
    - computer and modem

## 1.4 Guided Transmission Media: Twisted Pair and Coax

### UTP: unshielded twisted pair

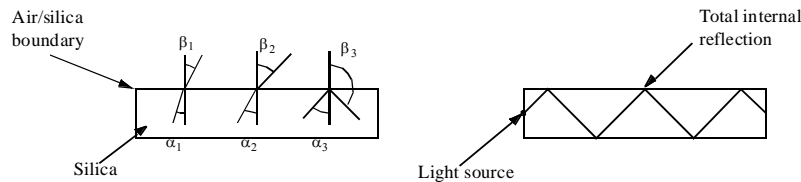


### Coaxial cable



## Fiber Optics

Three examples of a light ray from inside a silica fiber impinging on the air/silica boundary at different angles  
Light trapped by total internal reflection



### Types:

- **Multimode**
  - several rays with different angles ('modes')
- **Monomode**
  - fiber diameter reduced to few wavelengths of light
  - light can propagate in straight line

## 2 Analog and Digital Information Encoding and Transmission

Variants and examples:

		Transmission	
		analog	digital
Information Coding	analog (voice, music)	"old" telephone system (POTS) → AM, FM	ISDN (voice service) Internet Audio → PCM, DM, ...
	digital (texts, images)	modem (modulator demodulator) at analog telephone connection Radio Data System RDS → PAM, PPM, PFM, ... and V.21, V.22 bis, ..., V.32 bis, V.34.	traditional computer networks and applications ISDN (data service) → Manchester Encoding, ...

# Digital Information – Digital Transmission

Digital information at end system

- usually TTL-Logic ("1" : 3V, "0" : 0V)

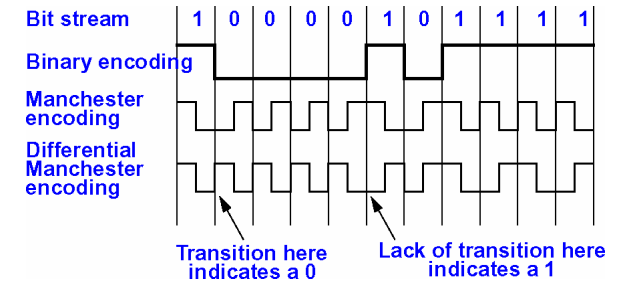
Digital transmission

- sender/receiver synchronization
- signal levels around 0V (lower power)
- ➔ Conversion

Coding techniques

- binary encoding, nonreturn to zero-level (NRZ-L)
  - 1: high level
  - 0: low level
- return to zero (RZ)
  - 1: clock pulse (double frequency) during interval
  - 0: low level
- ...
- Manchester Encoding
- Differential Manchester Encoding
- ...

# Binary Encoding



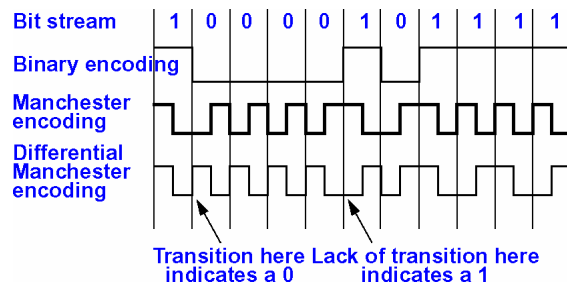
Binary encoding (Nonreturn to zero):

- "1": voltage on high
- "0": voltage on low

i. e.

- + simple, cheap
- + good utilization of the bandwidth (1 bit per Baud)
- no "self-clocking" feature

# Manchester Encoding

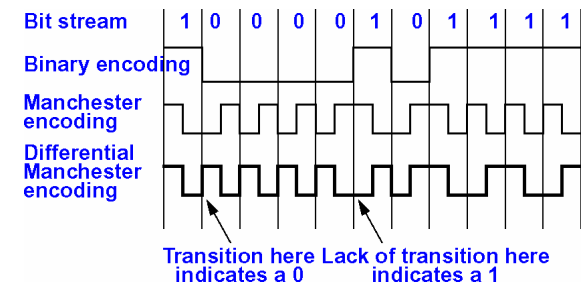


Bit interval is divided into two partial intervals: I1, I2

- "1": I1: high, I2: low
- "0": I1: low, I2: high
- + good "self-clocking" feature
- 0,5 bit per Baud

Application: 802.3 (CSMA/CD)

# Differential Manchester Encoding



Differential Manchester Encoding:

- bit interval divided into two partial intervals:
  - "1": no change in the level at the beginning of the interval
  - "0": change in the level
- + good "self-clocking" feature
- + low susceptibility to noise because only the signal's polarity is recorded. Absolute values are irrelevant.
- 0,5 bit per Baud
- complex

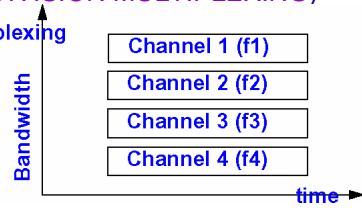
### 3 Multiplexing Techniques

The cost for implementing and maintaining either a narrowband or a wideband cable are almost the same  
 → multiplexing many conversations onto one channel

Two procedural classes:

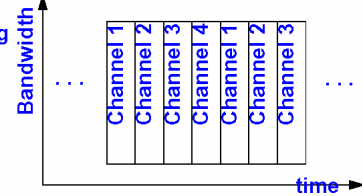
- FDM (FREQUENCY DIVISION MULTIPLEXING)

Frequency Division Multiplexing (FDM)



- TDM (TIME DIVISION MULTIPLEXING)

Time Division Multiplexing (TDM)



### Time Division Multiplexing

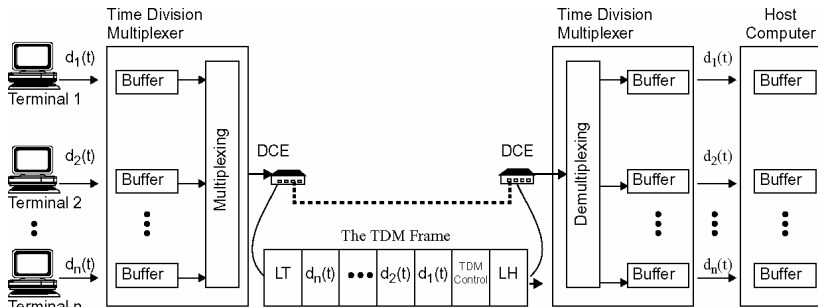
Principle:

- user receives a time slot
- during this time slot he has the full bandwidth

$$\sum_{i=1}^n d_i(t) = d_0(t)$$

Application:

- multiplexing of end systems, but also
- in transmission systems



LT: Link Trailer, LH: Link Header,  $d_i(t)$ : Fixed, predetermined slots for each device, TDM Control: Identification of specific TDM controls (may not exist on some TDMs)

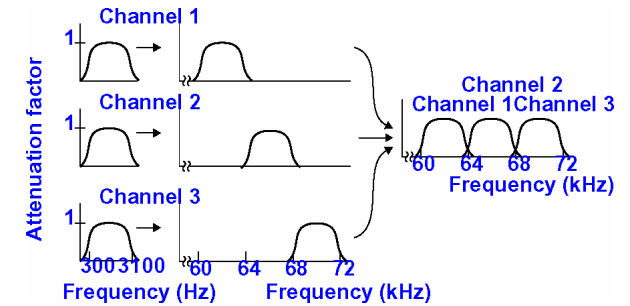
### Frequency Multiplexing

Principle:

- frequency band is split between the users
- each user is allocated one frequency band

Application:

- example: multiplexing of voice telephone channels: phone, cable-tv



- filters limit voice channel to 3 000 Hz bandwidth
- each voice channel receives 4 000 Hz bandwidth
  - 3 000 Hz voice channel
  - 2 x 500 Hz gap (guard band)

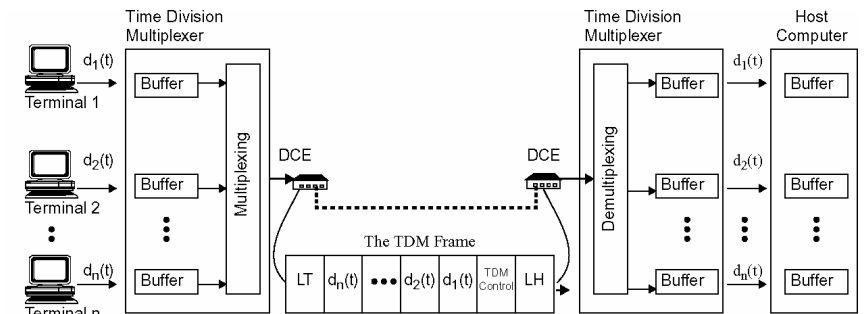
→ despite guard band adjacent channels overlap, noise

### Multiplexer and Concentrator

MULTIPLEXER:

- INPUT from various links in predefined order
- OUTPUT at one single link in the same order

$$\sum_{i=1}^n c_i^N = c^{OUT}$$

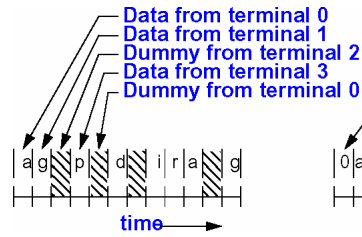


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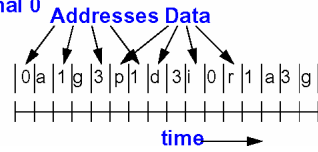
Disadvantage: waste of time slots if station is not sending

# Multiplexer and Concentrator

Multiplexer:



Concentrator:



Concentrator:

- INPUT from several links
- OUTPUT at one single link
- no fixed slot allocation,  
instead sending of (station addresses, data)

$$\sum_{i=1}^n C_i^N > C^{OUT}$$

PROBLEM: All stations use maximum speed for sending

- "Solution": internal buffers